

(12) INTERNATIONAL APPLICATION PUBLISHED UNDER THE PATENT COOPERATION TREATY (PCT)

(19) World Intellectual Property Organization International Bureau



(43) International Publication Date
16 June 2005 (16.06.2005)

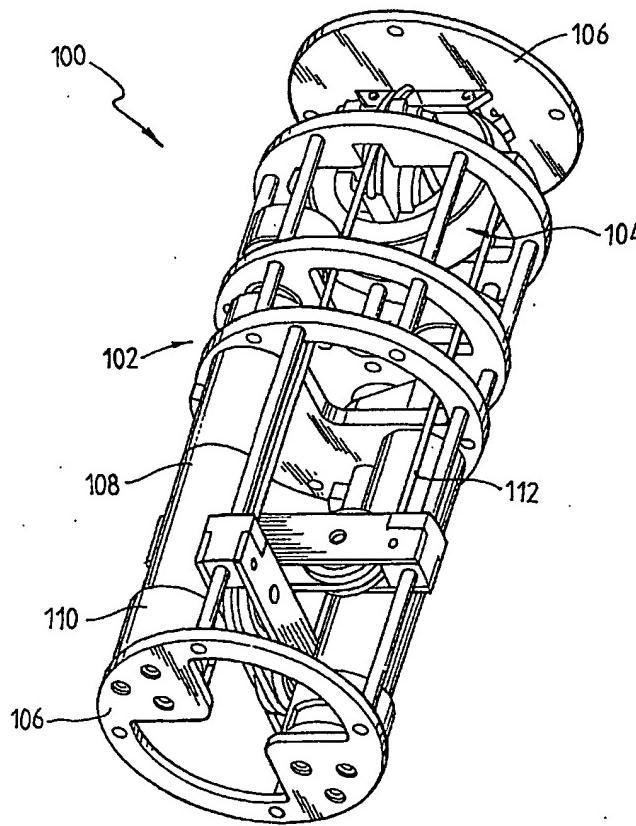
PCT

(10) International Publication Number
WO 2005/053912 A1

- (51) International Patent Classification⁷: B25J 9/00,
9/06, 9/08
- (21) International Application Number:
PCT/AU2004/001683
- (22) International Filing Date: 1 December 2004 (01.12.2004)
- (25) Filing Language: English
- (26) Publication Language: English
- (30) Priority Data:
2003906638 1 December 2003 (01.12.2003) AU
2004906445 10 November 2004 (10.11.2004) AU
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- (81) Designated States (*unless otherwise indicated, for every kind of national protection available*): AE, AG, AL, AM, AT, AU, AZ, BA, BB, BG, BR, BW, BY, BZ, CA, CH, CN, CO, CR, CU, CZ, DE, DK, DM, DZ, EC, EB, EG, ES, FI, GB, GD, GE, GH, GM, HR, HU, ID, IL, IN, IS, JP, KE, KG, KP, KR, KZ, LC, LK, LR, LS, LT, LU, LV, MA, MD, MG, MK, MN, MW, MX, MZ, NA, NI, NO, NZ, OM, PG, PH, PL, PT, RO, RU, SC, SD, SE, SG, SK, SL, SY, TJ, TM, TN, TR, TT, TZ, UA, UG, US, UZ, VC, VN, YU, ZA, ZM, ZW.
- (84) Designated States (*unless otherwise indicated, for every kind of regional protection available*): ARIPO (BW, GH, GM, KE, LS, MW, MZ, NA, SD, SL, SZ, TZ, UG, ZM, ZW), Eurasian (AM, AZ, BY, KG, KZ, MD, RU, TJ, TM),

[Continued on next page]

(54) Title: A METHOD FOR CONTROLLING A SYSTEM FORMED FROM INTERDEPENDENT UNITS



WO 2005/053912 A1

(57) Abstract: A system formed from a plurality of interdependent units 200A to 200E are controlled to achieve an outcome by establishing a desired action for each unit responsive to the outcome but independently of the desired action of the other units. The control methodology has particular application for robotic manipulators.



European (AT, BE, BG, CH, CY, CZ, DE, DK, EE, ES, FI, FR, GB, GR, HU, IE, IS, IT, LT, LU, MC, NL, PL, PT, RO, SE, SI, SK, TR), OAPI (BF, BJ, CF, CG, CI, CM, GA, GN, GQ, GW, ML, MR, NE, SN, TD, TG).

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Published:

— *with international search report*